

# **Drawing in 2D**

**CSCI 4229/5229  
Computer Graphics  
Fall 2008**

# Coordinate Systems

- Cartesian coordinates
  - Most commonly used
  - Left or right handed
  - 2D is a trivial case in 3D
- Polar coordinates
  - Convenient in some instances
- Curvilinear Coordinates
  - Specialized applications

# 2D Cartesian Coordinate Systems

- World Coordinates
  - $Xmin - Xmax$  x  $Ymin - Ymax$
- Normalized Device Coordinates
  - $0-1$  x  $0-1$  or  $0-1$  x  $0-r$
  - may be isometric
  - Viewport  $Umin - Umax$  x  $Vmin - Vmax$
- Device coordinates
  - pixels, plotter increments
  - origin may be top-left

# Transformations

- World to Normalized Device Coordinates

$$u = (x - X_{min}) / (X_{max} - X_{min}) * (U_{max} - U_{min}) + U_{min}$$

$$v = (y - Y_{min}) / (Y_{max} - Y_{min}) * (V_{max} - V_{min}) + V_{min}$$

- Normalized Device to World Coordinates

$$x = (u - U_{min}) / (U_{max} - U_{min}) * (X_{max} - X_{min}) + X_{min}$$

$$y = (v - V_{min}) / (V_{max} - V_{min}) * (Y_{max} - Y_{min}) + Y_{min}$$

- $(x, y)$  may be outside  $(X_{min} - X_{max}, Y_{min} - Y_{max})$

# Vector Lines

- Line from  $(x_0, y_0)$  to  $(x_1, y_1)$
- Explicit
  - $y = (x-x_0)*(y_1-y_0)/(x_1-x_0) + y_0$
  - $x = (y-y_0)*(x_1-x_0)/(y_1-y_0) + x_0$
- Parameteric
  - $x = (1-f)x_0 + f x_1$
  - $y = (1-f)y_0 + f y_1$
  - $f = 0 \Rightarrow (x_0, y_0); \quad f = 1 \Rightarrow (x_1, y_1)$

# Vector Clipping

- Cohen-Sutherland Line Clipping
  - Determine region of start and end
  - Accept, reject or clip
- Parametric Line-Clipping Algorithm
  - Calculate parameter  $t$
  - $0 < t < 1$  requires clipping
- Sutherland-Hodgman Polygon Clipping
  - Clips edges of polygon
  - Successive clips to half planes

# Cohen-Sutherland Line Clipping

- Set bits to identify outside zones
- Trivial accept or reject
- Clip non-trivial cases
- Accept or reject

# Parametric Line Clipping

- Cohen-Sutherland may require up to 4 clips
- Parametric algorithm more efficient
  - Original Cyrus-Beck
  - Improved by Liang-Barsky
- Readily extends to 3D and irregular windows
- Basic equation for line from  $P_0$  to  $P_1$

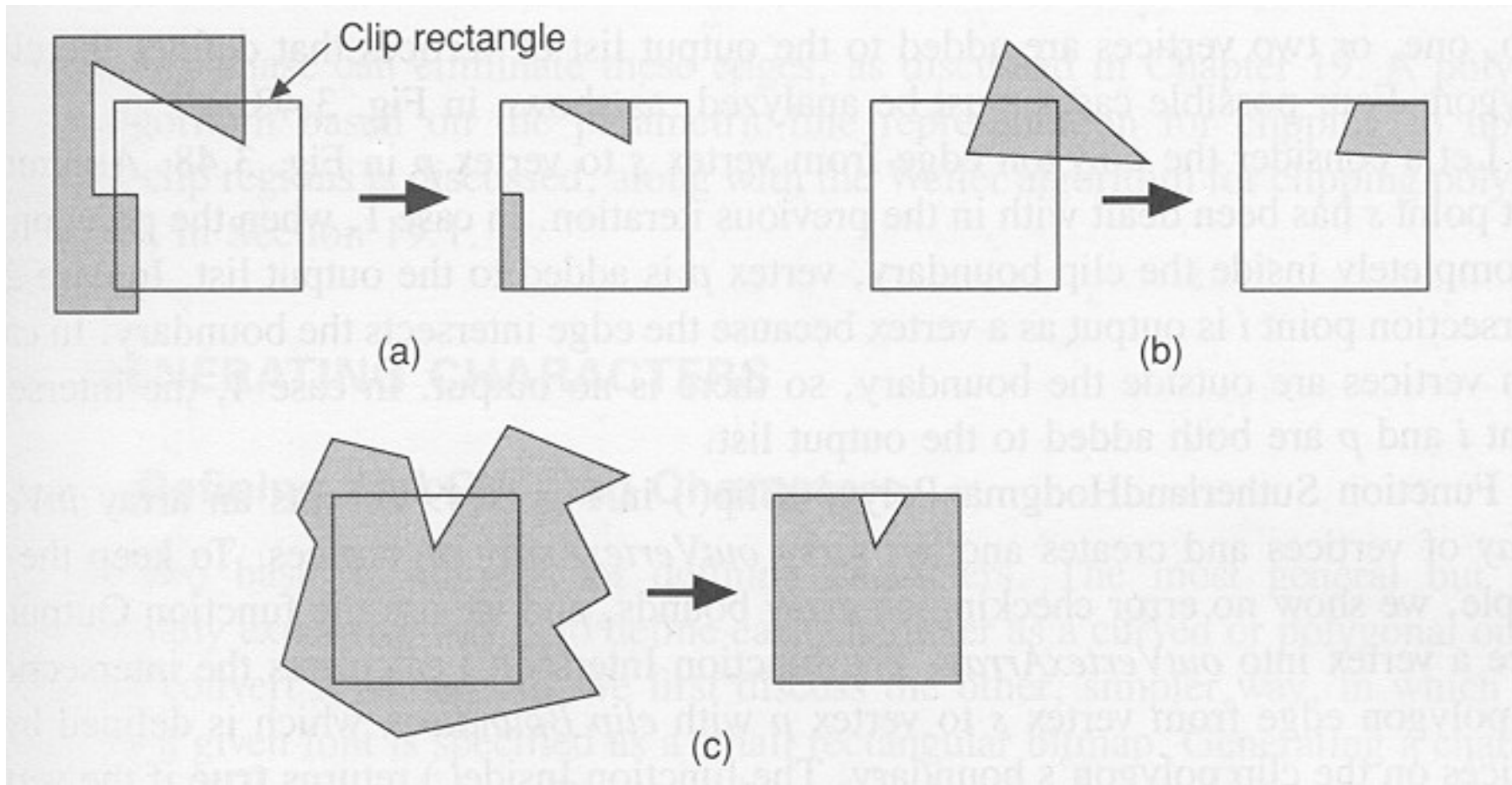
$$t = (N \cdot [P_0 - P_E]) / (N \cdot [P_0 - P_1])$$

$N$  is the outside normal

$P_E$  is on the edge



# Polygon Clipping Challenges



# Polygon Clipping Algorithm

