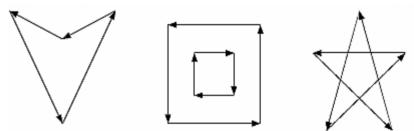
Polygons CSCI 4229/5229 Computer Graphics Summer 2025

Polygon Definitions

- A polygon is strictly a planar object
 - Plane defined as ax + by + cz = 1
 - Three distinct (x,y,z) points
 - One (x,y,z) point and a normal vector
 - Finite subset of plane defined by set of vertices
 - Vertexes must be in the plane
- In OpenGL you can specify 3D vertices
 - When vertexes are not in a plane, the results are implementation dependent

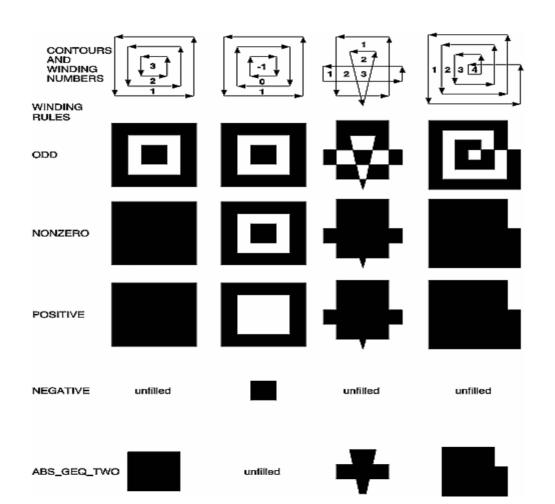
Convex vs. Concave

- Convex polygons: Given any two points \mathbf{a} and \mathbf{b} in the polygon $\mathbf{c} = f\mathbf{a} + (1-f)\mathbf{b}$ is also inside the polygon for any f in (0,1)
- Concave polygons: Some c is outside the polygon
- Concave examples:



OpenGL requires convex polygons

What is Inside?



Normals for Polygons

- Given 3 points in the plane P₁, P₂ and P₃
 - Normalize $(P_2-P_1)\times(P_3-P_1)$
 - Use any three distinct vertexes of the polygon not on a line
- True Gouraud shading
 - Calculate normals for all polygons

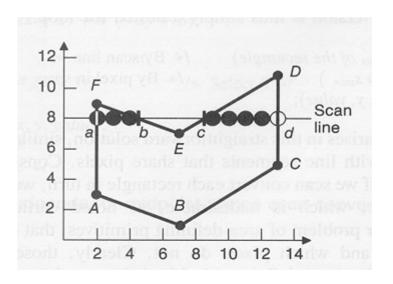




- At common vertexes, average all the normals
- Interpolate across polygons
- OpenGL normals are set at vertexes

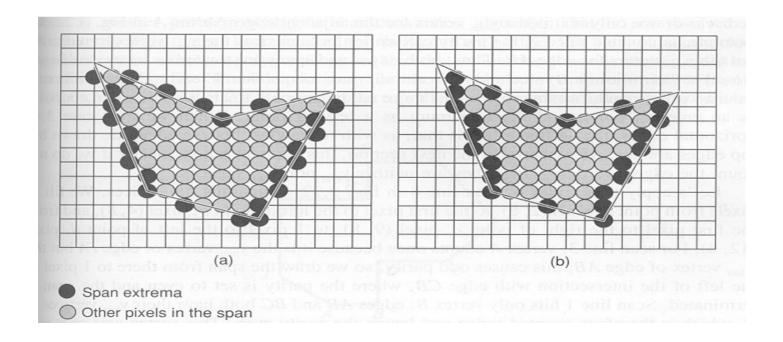
Scan Converting Polygons

- Draw horizontal lines to fill the polygon
- Pairs of points are interior
- Vertexes on a scanline is a problem
- Convex polygons are easy



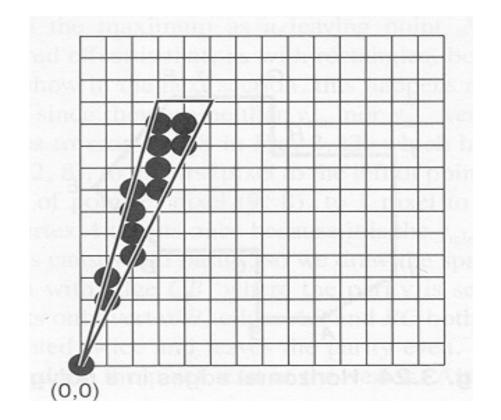
Deciding the Polygon Extent

- (a) Bresenham Outline
- (b) Strictly Interior Outline



Edge Coherence

- Scan lines intersects near the last scanline
- Slivers may be just a line



OpenGL Polygons

- glPolygonMode(type)
 - GL POINT draws vertexes
 - GL LINE draws outline
 - GL FILL fills polygon
- glPolygonStipple(mask)
 - 32x32 pixel (byte) mask
 - glEnable(GL_POLYGON_STIPPLE)